



NIETZ

Innovation + **Driving Tomorrow**

>> WHO WE ARE

NIETZ is one Leading Manufacturer of industrial automation products, with more than millions units sold worldwide, established 2005 Shanghai, China. We are committed to building long-lasting and successful business relations with our partners, has gained good reputation and deep influence.

We aim to provide the best quality, unmatched reliability and low price in our services and our products. We aim to reduce your costs, streamline manufacturing, to improve productivity.

The products of NIETZ are Variable Frequency Inverters, AC Servo System, Soft Starter, Planetary Gearboxes and Complete Device, The products NIETZ are technological advanced products and it has quite wide product range and already used widely in various applications such as textile machine, air compressor, hoist, packing machine, printing machine, electronic machine and other industries, which exported to over 40 countries and regions such as Europe, South America, Southeast Asia, Middle East and so on.

NIETZ always aims to be the professional driving solution provider and your mutual-benefit partner.















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NL1000

Micro & Economic

- Small Dimension, Low Cost
- Terminals Uncovered, Easy to Use and Wiring
- DIN-Rail Mounting and Wall Mounting
- Support MODBUS via RS485
- V/F Control; Buit-in PID Control
- Frequency Range 0.1...999.9Hz



	Item			Specifications		
	Power Supply	Rated Voltage	220 VAC, 50/60I 220 VAC, 50/60I	Hz, 1 Phase Input and 3 Phase Output Hz, 1 Phase Input and 1 Phase Output Hz, 3 Phase Input and 3 Phase Output Hz, 3 Phase Input and 3 Phase Output		
		Voltage Range	220 VAC 380 VAC	170-240 VAC 330-440 VAC		
	Voltage Range		220 VAC 380 VAC	0-240 VAC 0-380 VAC		
	•	Frequency Range	0.10-999.9 Hz			
	Control Mode		V/F Control, Spa	ace Vector Control		
	Indication		, ,	s/Alarm definition/interactive guidance: eg, ig, the output frequency/ current, DC bus voltage, e and so on.		
	Output Frequency F	Range	0.10-999.90 Hz			
	Frequency Setting Resolution		Digital Input Analog Input	0.1 Hz 0.1% of Max. Output Frequency		
Ē	Output Frequency Accuracy		0.1 Hz			
atio	V/F Control		Setting V/F Curv	ve to Satisfy Various Load Requirements		
ecific	Torque Control		Auto Increase Manual Increase	Auto raise Torque by Loading Condition Enable to Set 0.1-20.0% of Raising Torque		
Control Specification	Multi-Functional Output Terminal		Counter, Externa	One Multi-Fuction Output Terminal for Displaying of Running, Zero Speed, Counter, External Abnormity, Program Operation and Other Information and UP / DOWN Fuction and Emergency Stop and Other Functions.		
Ö	Multi-Functional Input Terminal		Four Multi-Fuction Input Terminals, Realizing Functions Including 15 Sections Speed Control, Program Running, 4 Section Acceleration / Deceleration Speed Switch, Warnings.			
	Accel/Decel Time		0-999.9s Accele	ration/Deceleration Time can be Set Individually		
Others Functions	Frequency Setting		Analog input Digital Input Note	0 to 10V, 0to 20mA can be Selected. Input Using the Setting Dial of the Operation Panel or RS485 or UP/DOWN. AVI Terminals can be Used to Select an Analog Voltage Input (0-10V) and Analog Current Input (4-20mA) through the Switch J2.		
rs F	Multi-Speed		4 Multi-Fuction	Input Terminals, 15 sections Speed can be Set		
the	Automatic Voltage	Regulation	Automatic Voltage Regulation Function can be Selected			
0	Counter		Built-in 2 Group of Counters			
<u>_</u>	Overload		150%, 60 s (Constant Torque)			
ctio ion	Over Voltage		Over Voltage Protection can be Selt.			
Protection Function	Under Voltage		Under Voltage F	Under Voltage Protection can be Set.		
도고	Other Protections		Output Short Circuit, Over Current and Parameter Lock and so on.			
	Ambient Temperate	ure	-10 to 40°C (Non-Condensing)			
ent	Ambient Humidity		Max. 95% (No-C	Condensing)		
Environment Installation	Altitude		Lower Than 100	0m		
viro tall.	Vibration		Max. 0.5G			
En	Cooling Mode		Forced Air Cooli	ing.		
	Protection Class		IP20			
	Installation Mode		Wall-Mounted of	or Standard 35mm Rail Mounting (Below 5.5kW)		





AT20

General Purpose, Compact

- Various Control Version, V/F, Sensorless
 Vector and Cloosed Loop Vector Control
- Built-in braking unit up to 450kW (optional)
- Support MODBUS RS485, ProfiNet is Selectable
- Digital and analogue I/O optional cards
- Support different PG cards, including resolover
- Suitable AC Inductiion Motor, Permanent Magnet Synchronous Motor is selectable

	Item	Specifications				
	Control Mode	V/F Control Sersorless Flux Vector Control, SFVC Closed-Loop Vector Control, FVC, Above 3.7kW				
	Max. Frequency	0.0-600.0 Hz				
	Carrier Frequency	0.5 kHz-8.0 kHz The Carrier Frequency is Automatically Adjusted Based on the Load Features.				
	Input Frequency Resolution	Digital Setting 0.01 Hz Analog Setting Max. Frequency x 0.025%				
	Start Torque	G Type 0.5 Hz / 150%, SVC P Type 0.5 Hz / 100%				
	Speed Range	1:100, SVC				
	Speed Stability Accuracy	±0.5%, SVC				
uc	Overload capacity	G Type 60s for 150% of the Rated Current, 3s for 180% of the Rated Current. P Type 60s for 120% of the Rated Current, 3s for 150% of the Rated Current.				
nctic	Torque boost	Auto-Boost; Customized Boost: 0.1%~30.0%				
Basic Function	Ramp Mode	Straight-Line Ramp. Four Groups of Acceleration/Deceleration Time with the Range of 0.00-6500.0s				
B	DC Braking	DC Braking Frequency 0.00Hz~Maximum frequency Braking Time 0.0s~36.0s Braking Action Current Value 0.0%~100.0%				
	JOG control	JOG Frequency Range 0.00 Hz-50.00 Hz JOG Acceleration/Deceleration Time: 0.0s~6500.0s				
	Simple PLC, Multiple Preset Speeds	It Implements up to 16 Speeds via the Simple PLC Function or Combination of Terminal States				
	Onboard PID	It Realizes Process Controlled Closed Loop Control System Easily				
	Auto voltage regulation (AVR)	It Can Keep Constant Output Voltage Automatically when the Mains Voltage Changes				
	Overvoltage / Overcurrent Stall Control	The current and voltage are limited automatically during the running process so as to avoid Frequent Tripping Due to Over Voltage/Over Current.				
	Rapid Current Limit	It Helps to Avoid Frequent Over Current Faults of the AC Drive.				
	Torque Limit and Control	It can Limit the Torque Automatically and Prevent Frequent Over Current Tripping During the Runing Process. Torque Control can be Implemented in the FVC Mode.				
70	High Performance	Control of Asynchronous Motor are Implemented Through the High-Performance Current Vector Control Technology.				
Individualized Functions	Rapid Dip Ride Through	The Load Feedback Energy Compensates the Voltage Reduction so That the AC Drive can Continue to Run for a Short Time				
ivid	Support for Multiple PG Card	Support for Differential Input PG Card, Resolver PG Card, Rotating Transformer PG Card				
Für	Rapid Current Limit	It Helps to Avoid Frequent Over Current Faults of the AC Drive.				
	Timing Control	0.0-6500.0 min.				
	Communication Methods	RS 485 standard, ProfiNet is selectable				
	Command Source	Operation Panel / Control Terminals / Serial Communication Port You can Perform Switchover Between these Sources in Various Ways.				
	Frequency Source	There are Ten Frequency Sources. Digital Setting, Analog Voltage Setting, Analog Current Setting, Pulse Setting, Serial Port Setting. You can Perform Switchover Between these Sources in Various Ways.				
Running	Input Terminal	Standard: 5 Digital Input Terminals (Below 5.5kW)/6 Digital Input Terminals (Above 7.5kW); 1 Analog Input Terminal (Below 5.5kW)/2 Analog Input Terminals (Above 6.5kW); 1 Voltage Input (Only Support for 0-10V, Above 7.5kW), 1 Voltage Input (0-10V) or Current Input (4-20mA)				
Rur	Output Terminal	1 High-Speed Pulse Output Terminal (Open-Collector), Above 3.7kW. 1 Relay Output Terminal (Below 5.5kW)/2 Relay Output Terminals (Above 7.5kW) 1 Analog Output Terminal (3.7-5.5kW)/2 Analog Output Terminal (Above 7.5kW), Support for 4-20mA Current Output or 0-10V Voltage Output				

NZ2000

General Purpose, Sensorless Vector Control

- Auto Identification, Simple to use
- PID Process Control, Multi-Function I/O
- Heavy Duty Use (3s 180%, 60s 150%)
- Support MODBUS, EtherCAT is selectable
- Power Range 0.4-280 kW
- Drives AC Induction Motor; Permanent Magnet Synchronous Motor is Selectable







	Item	Specifications						
	Control Mode	V/F Control						
	Control Mode	Sersorless Flux Vector Control, SFVC						
	Max. Frequency	Vector Control 0.0-320.0 Hz V/F Control 0.1-3200 Hz						
	Carrier Frequency	1.0 kHz-16.0 kHz The Carrier Frequency is Automatically Adjusted Based on the Load Features.						
	Input Frequency Resolution	Digital Setting 0.01 Hz Analog Setting Max. Frequency x 0.025%						
	Start Torque	G Type 0.5 Hz / 150%, SFVC P Type 0.5 Hz / 100%						
	Speed Range	1:100, SFVC						
	Speed Stability Accuracy	±0.5%, SFVC						
	Overload Capacity	G Type 60s for 150% of the Rated Current, 3s for 180% of the Rated Current. P Type 60s for 120% of the Rated Current, 3s for 150% of the Rated Current.						
	Torque Boost	Fixed Boost; Customized Boost 0.1%~30.0%						
	Ramp Mode	Straight-Line Ramp; S-Curve Ramp Four Groups of Acceleration/Deceleration Time with the Range of 0.00-6500.0s						
u	DC Braking	DC Braking Frequency 0.00Hz~Maximum frequency Braking Time 0.0s~100.0s Braking Action Current Value 0.0%~100.0%						
Basic Function	JOG control	JOG Frequency Range 0.00 Hz-50.00 Hz JOG Acceleration/Deceleration Time: 0.0s~6500.0s						
sic	Simple PLC, Multiple Preset Speeds	It Implements up to 16 Speeds via the Simple PLC Function or Combination of Terminal States						
Ba	Onboard PID	It Realizes Process Controlled Closed Loop Control System Easily						
	Auto voltage regulation (AVR)	It Can Keep Constant Output Voltage Automatically when the Mains Voltage Changes						
	Overvoltage / Overcurrent Stall Control	The current and voltage are limited automatically during the running process so as to avoid Frequent Tripping Due to Overvoltage/Over Current.						
	Rapid Current Limit	It Helps to Avoid Frequent Over Current Faults of the AC Drive.						
	Torque Limit and Control	It can Limit the Torque Automatically and Prevent Frequent Over Current Tripping During the Runing Process.						
	High Performance	Control of Asynchronous Motor are Implemented Through the High-Performance Current Vector Control Technology.						
	Running Command Channel	Given by the Panel, Control Terminals, Serial Communication Port, can be Switched by Many Ways.						
	Frequency Source	There are Ten Frequency Sources. Digital Setting, Analog Voltage Setting, Analog Current Setting, Pulse Setting, Serial Port Setting, You can Perform Switchover Between these Sources in Various Ways.						
	Auxiliary Frequency Source	10 kinds of Frequency Sorce, can be easlly realize Micro Adjust, Frequency Synthesizer						
	Timing Control	0.0-6500.0 min.						
	Communication Methods	RS 485, EtherCAT is optional						
Output	Input Terminal	6 Digital Input Terminals, One of Which Supports up to 100 kHz High-Speed Pulse Input (Optional). 2 Analog Input Terminals, One of Which Only Supports 0-10V Voltage Input and the Other Supports 0-10V Voltage Input or 4-20mA Current Input.						
Input & Out	Output Terminal	Digital Output Terminal Relay Output Terminal Analog Output Terminal, That Supports 0-20mA Current Output or 0-10V Voltage Output						
'n	Protection Function	Motor Shourt-Circuit Detection at Power-On, Output Phase Loss Protection, Over-Current Protection , Overheat Protection and Overload						
Others	Key Locking and Function Selection	It can Lock the Keys Parlially or Completelly and Define the Function Range of Some Keys so as to Prevent Mis-Function.						
	Protection Class	IP20						



NZ8000

High Performance & Powerfull, Heavy Duty

- Various Control Version, V/F, Sensorless Vector and Cloosed Loop Vector Control
- Modbus RS 485, Profibus-DP, CANopen Communication Mode
- Flexible Programmable I/Os
- Heavy Duty 150% 60s, 180% 3s
- Wide Operating Voltage 220 to 690 VAC

in in in	Item	Specifications	11127				
	Control Mode	V/F Control Sersorless Flux Vector Control, SFVC Closed-Loop Vector Control, FVC, Above 3.7kW					
	Max. Frequency	Vector Control 0.0-320.0 F V/F Control 0.0-3200.0					
	Carrier Frequency	1.0 kHz-16.0 kHz The Carrier Frequency is Automatically Adjusted Based on tl	he Load Features.				
	Input Frequency Resolution	Digital Setting 0.01 Hz	uency x 0.025%				
	Start Torque		50%, SFVC; 0.0 Hz / 180%, FVC				
	Speed Range	1:100, SFVC / 1:1000, FVC					
	Speed Stability Accuracy	±0.2%, SFVC / ±0.02%, FVC					
	Torque Control Accuracy	±5%, Cloosed-Loop Vector Cotrol FVC Mode					
=	Overload capacity	G Type 60s for 150% of the Rated Current, 3s for 180% of the Rated Current P Type 60s for 120% of the Rated Current, 3s for 150% of the Rated Current					
2	Torque boost	Fixed-Boost; Customized Boost: 0.1%~30.0%					
	Ramp Mode	Straight-Line Ramp.; S-Curve Ramp; Four Groups of Acceleration/Deceleration Time with the Range of 0.00-6500.0s					
3	DC Braking	DC Braking Frequency 0.00Hz~N Braking Time 0.0s~100.0 Braking Action Current Value 0.0%~100					
	JOG control	JOG Frequency Range 0.00 Hz-5t JOG Acceleration/Deceleration Time 0.0s~6500					
	Onboard Multiple Preset Speeds	It Implements up to 16 Speeds via the Simple PLC Function or Combination of Terminal States					
	Onboard PID	It Realizes Process Controlled Closed Loop Control System Easily					
	Auto voltage regulation (AVR)	It Can Keep Constant Output Voltage Automatically when the Mains Voltage Changes					
	Auto voltage regulation (AVIV)	The current and voltage are limited automatically during the running process so as to avoid					
	Overvoltage / Overcurrent Stall Control	Frequent Tripping Due to Over Voltage/Over Current.					
	Torque Limit and Control	It can Limit the Torque Automatically and Prevent Frequent Over Current Tripping During the Runing Process. Torque Control can be Implemented in the FVC Mode.					
	High Performance	Control of Asynchronous Motor and Synchronous Motor are Implemented Through the High Performance Current Vector Control Technology.					
ns	Rapid Dip Ride Through	The Load Feedback Energy Compensates the Voltage F to Run for a Short Time	Reduction so That the AC Drive can Continue				
Functions	Support for Multiple PG Card	Differential Input PG Card / Resolver PG Card / Rotating Tra UVW Differential Input PG Card / OC Input PG Card	ansformer PG Card				
ヹ	Rapid Current Limit	It Helps to Avoid Frequent Over Current Faults of the AC Dr	rive.				
	Timing Control	0.0-6500.0 min.					
	Communication Methods	Modbus (Standrad), Profibus-DP, CANopen					
	Running Command Source	Operation Panel / Control Terminals / Serial Communication You can Perform Switchover Between these Sources in Varie					
	Frequency Source	Digital Setting, Analog Voltage Setting, Analog Current Sett Pulse Setting, Serial Port Setting. You can Perform Switchov	<u>o</u> .				
n N	Input Terminal	8 Digital Input Terminals, One of Which Supports up to 100 2 Analog Input Terminal, One of Which Only Supports 0-10 the Other Suppports 0-10V Voltage Input or 4-20 mA Current) kHz High-Speed Pulse Input IV Voltage Input and				
	Output Terminal	1 High-Speed Pulse Output Terminal (Open-Collector) that Su 1 Digital Output Terminal 2 Relay Output Terminal 2 Analog Output Terminal - that Supports 0-20mA Current					
	Protection Function	Motor shourt-circuit detection at power-on, output phase loss,	, over-current, overheat, under voltage and overload				
			-				

\overline{NZS} Power range Max. up to 110 kW

IP65/IP54 Class. V/F and Sensorless Vector Contro

- High Level Protection Class, Outdoor Application
- Various Version Control Mode, V/F and SFVC
- Pumps Application/General Purpose Selectable
- Compact, Rugged Design. It can be Directly Installed on the Motors or on Virtually any Other Mounting Surface Based on the Application Requirements.
- Master/slave system makes this easy to set pumps



Control Mode Max. Frequency Carrier Frequency Input Frequency Resolution Start Torque Speed Range Speed Stability Accuracy Overload Capacity Torque Boost	Vector Control V/F Control 1.0 kHz-16.0 kHz The C adjusted based on the Digital Setting Analog Setting G Type P Type 1:10 ±0.5	0.01 Hz Max. Frequency x 0.025% 0.5 Hz / 150%, SFVC 0.5 Hz / 100% 0, SFVC %, SFVC / 3s for 180% of rated current	Digital Setting Analog Setting	0.1-400 Hz 1.0 kHz-15.0 kHz 0.1 Hz Max. Frequency x 0.1% 0.5 Hz / 100%	
Carrier Frequency Input Frequency Resolution Start Torque Speed Range Speed Stability Accuracy Overload Capacity	V/F Control 1.0 kHz-16.0 kHz The Cadjusted based on the Digital Setting Analog Setting G Type P Type 1:10 ±0.5 G Type 60s for 150%	0.1-3200 Hz Carrier frequency is automatically load features. 0.01 Hz Max. Frequency x 0.025% 0.5 Hz / 150%, SFVC 0.5 Hz / 100% 0, SFVC %, SFVC / 3s for 180% of rated current	Digital Setting Analog Setting	1.0 kHz-15.0 kHz 0.1 Hz Max. Frequency x 0.1%	
Input Frequency Resolution Start Torque Speed Range Speed Stability Accuracy Overload Capacity	adjusted based on the Digital Setting Analog Setting G Type P Type 1:10 ±0.5 G Type 60s for 150%	load features. 0.01 Hz Max. Frequency x 0.025% 0.5 Hz / 150%, SFVC 0.5 Hz / 100% 0, SFVC %, SFVC / 3s for 180% of rated current	Digital Setting Analog Setting	0.1 Hz Max. Frequency x 0.1%	
Start Torque Speed Range Speed Stability Accuracy Overload Capacity	Analog Setting G Type P Type 1:10 ±0.5 G Type 60s for 150%	Max. Frequency x 0.025% 0.5 Hz / 150%, SFVC 0.5 Hz / 100% 0, SFVC %, SFVC / 3s for 180% of rated current	Analog Setting	Max. Frequency x 0.1%	
Speed Range Speed Stability Accuracy Overload Capacity	P Type 1:10 ±0.5 G Type 60s for 150%	0.5 Hz / 100% 0, SFVC %, SFVC / 3s for 180% of rated current		0.5 Hz / 100% / /	
Speed Stability Accuracy Overload Capacity	±0.5 G Type 60s for 150%	%, SFVC / 3s for 180% of rated current		/	
Overload Capacity	G Type 60s for 150%	/ 3s for 180% of rated current		/	
, ,					
Torque Boost		/3s for 150% of rated current	60s for 120%/3s fo	or 150% of rated current	
	Fixed Boost; Customiz	zed Boost 0.1%~30.0%		by loading condition;).0-20% of rasing torque	
Ramp Mode		tion/Deceleration Time with	Straight-Line Ramp, the Range of 0.0-999.9.0s		
DC Braking	Braking Time	0.0s~100.0s	DC Braking Freque Braking Time Braking action curre	0-25.0s	
JOG control	Frequency Range Acce-tion/deceleration	0.00 Hz-50.00 Hz n time 0.0-6500.0s	Frequency range Acce-tion/decelera	0.0 Hz-Max.frequency ation time 0.0-999.9s	
Simple PLC, Multiple Preset Speeds			4 multiple termina to 15 speeds	als, It implements up	
Onboard PID	It realizes process Co system easily	ntrolled Closed Loop Control		Built-in PID	
Auto voltage regulation (AVR)			Automatic voltage selected as require	regulation function can be ed	
Overvoltage / Overcurrent Stall Control	during the running p	rocess so as to avoid	The overvoltage p	protection can be set	
Frequency Source	set, analog current set,	pulse set, serial port set, you	Analog input 0 to 10V, 0to 20mA can be selected directly set by keyboard, RS485 set, up/down set and others various ways		
Input Terminal	high-speed pulse Input (1 of which only supports	Optional).2 analog input terminals, 0-10V voltage Input and the other		ut terminals, 1 analog input termin nge input or 4-20mA current input.	
Output Terminal	1 relay output terminal	1 relay output terminal		2 relay output terminal (0.75-5.5 kW) 1 relay output terminal (7.5kw and above)	
Others			Built-i	in 2 groups of counters	
Protection Function	Motor shourt-circuit det	ection at power-on, output phase le	oss, over-current, over	heat, under voltage and overload	
Communication Methods					
				oor	
<u> </u>					
	· ·				
	DC Braking DOG control Simple PLC, Multiple Preset Speeds Dinboard PID Auto voltage regulation (AVR) Divervoltage / Overcurrent Stall Control Frequency Source Input Terminal Dutput Terminal Others Protection Function	A Groups of Accelerate the Range of 0.0-650 DC Braking DC Braking Frequence Braking action current of Braking action cur	A Groups of Acceleration/Deceleration Time with the Range of 0.0-6500.0s DC Braking Frequency	A Groups of Acceleration/Deceleration Time with the Range of 0.0-6500.0s DC Braking Terquency Braking Time DC	









PDS-7

Pumps Drives -Wall-Mounted Type

220 / 380VAC; 1HP - 3HP

- Compact, Directly Mounted on Motors
- Using DSP high-speed digital processor and high-performance IGBT, the circuit is mature and the performance is stable.
- Easy to Use, Suitable to Any Pumps
- Built-in PID, PLC; Max.Frequency up to 999.9 Hz
- V/F Control Mode; Performance Load Capacity

Itom					100 11		
ŀ		Item		222146		pecifications	
	Down	or Cumply	Rated Voltage			out and 3 Phase Output out and 3 Phase Output	
	POW	er Supply	Voltage Range	220 VAC 380 VAC		170-240 VAC 330-440 VAC	
	Outp	out	Voltage Range	220 VAC 380 VAC		0-240 VAC 0-380 VAC	
	Out	Frequency Range				0.0-999.9 Hz	
	Cont	rol Mode				V/F Control	
	Carri	Carrier frequency setting				0.5-16.0 kHz	
		Output Frequency Range				0.0-999.90 Hz	
		Frequency	Setting Resolution	Digital Inp Analog Inp		0.1 Hz 0.025% of Max. Output Frequency	
		Startup To	rque	G type P type		0.5 Hz /150% 0.5 Hz / 100%	
		Speed Range		1:100			
		Overload Capacity		G type 150% of rated current, 60s; 180% of rated current 120% of rated current, 60s; 150% of rated current			
		Torque Boost Acce-tion & deceleration curve time		Manual mode 0.1%~30.0% 0-999.9s, 4 types acc-tiion/deceleration time			
	n	Acce-tion &	deceleration curve time		**		
	Basic Specification	DC Braking		DC Braking Frequency Braking Time Braking action current value		0.0 Hz-Max.frequency 0.0-36.0s 0.0~100.0%	
1		JOG control		JOG frequency range Acce-tion/deceleration time		0.0Hz~50.00Hz 0.0s~999.9s	
	Ф	Multi-Spee	ed, PLC operation		nts multi-speeds via on of terminal states	a the built-in PLC function or	
		Onboard PID software		Integrated enhanced PID control algorithm: with sleep, wake-up, antifreeze, disconnection detection, high and low pressure alarm, water shortage detection, automatic operation after water supply / fault reset and other functions			
		Automatic Voltage Regulation		It can keep constant output voltage automatically when the mains voltage changes			
		Communication		RS-485			
		Protection	Functions	I/O phase loss protection, over current protection, over voltage protection, under voltage protection, overheat protection and overload protection			
	ers	Input Term	inals	2 digital input terminals; 2 analog,each of which supports 0~10V or 4~20mA current input;			
	Input & Output, others	Frequency	Source	Digital, analog voltage, analog current, serial port. Can be switching in various ways.			
	utp	Command	Source	Operation	panel/Control term	inals/Serial communication port	
	t & O	Output So	urce		r output terminal put terminal		
1	ndı	Protection	Class			IP20	
STATE OF THE PERSON	=	Installation	Mode	Mounted on the Motor Directly or Wall-Mounted			

PDS-7 wall-mounted frequency converter for fixedspeed equipped with asynchronous motors. Its a new generation of high-end intelligent integrated compact water supply special products independently researched & developed by NIETZ.

It can be installed on various brands of Pump Motor terminalboxes, and can be accessed in various types of sensor signal, saving panel space and cost.

- Newly developed SOFTWARE 2.0 platform, using modular design, software performance is excellent and stable.
- Adopt a new space vector algorithm with a reliable protection mechanism.
- Integrated enhanced PID control algorithm: with sleep wake-up, antifreeze, disconnection detection, high & low pressure alarm, water shortage detection, water shortage shutdown, automatic operation after water supply, automatic fault reset and other functions.
- Featuring simple operation, good reliability, low noise and high performance.

TECHNICAL FEATURES

	4	ni;	ter, mm2	gnet	▼ <i>5</i>	*)q
	Power, KM	Main Circuit Wire Diam	Air Circuit Breaker, A	Electromagnes	Rated Input	Rated Output
		(((((
220V ±15%	0.75	1.0	25	13	7.2	5
1 Phase Input,	1.5	1.5	25	18	10	7
3 Phase output	2.2	2.0	25	25	13	9
2016						
380V ±15%	0.75	0.5	10	6	3.5	2.1
	1.5	1.0	10	9	5	3.7
	2.2	1.0	10	10	5.8	5
	Patricia	10				

\\\P9

Multi-Pumps Control

- V/F Control, Sensorless Vector Control
- Controls max. 4 water pumps after add relay output
- Heavy Duty Use (3s 180%, 60s 150%)
- Support MODBUS via RS485
- 24 VDC power supply support to Current sensor
- STO Function more Effecient Protect the Pumps



Advantage and Features

WP-9 multiple pump Variable Speed Drive is for controls multi-pumps, max. 4 in parallel, The inverter selects which pumps will operate in order to keep/control the process value of the pumping system. An alternation between their activation is also performed, making it possible an equal use of the pumps.

▶ Features

- Full protection for pumping systems and maximized usability through special functions
 The ▲▼ key directly adjusts the target pressure
- Power off, then when the power is restored, it will automatically restart the running function.
- Extended relay output can achieve one inverter control 4 constant pressure water supply pump.
- 24VDC power supply to power the current sensor.
 The Drive has the intelligent judgment function of dormancy.
- English keyboard displays target value and feedback value.
- It can be extended to 4 pumps for water supply, including stabilized pressure pump and variable frequency pump.
- It supports the online selection function of feed-1 pump and 1 frequency conversion linkage control completes constant pressure water supply function.
- The keyboard can start the constant pressure water supply control function, can have the stop function and the fault reset function.

Security Alarm Function <

- High water pressure alarm function, low water pressure alarm function
- Protection function of water shortage
- Antifreeze function
- Detect sensor disconnection
- Automatic reset of water shortage fault
 Multi-pump control, fault pump is manually cut off

	<u></u>	Optional Water Supply Card can be control Max. 4 pumps
AC BU		

	Item	Specificat	ions			
	Control Mode	V/F Control, Sensorless Verct				
	Max. Frequency	0.0-600.0				
	Carrier Frequency	0.5 kHz-12.0 kHz The Carrier Frequency is Adjusted Based on the Load Features.	Automatically			
	Input Frequency Resolution	Digital Setting Analog Setting	0.01 Hz Max. Frequency x 0.025%			
	Start Torque	G Type P Type	0.5 Hz / 150% 0.5 Hz / 100%			
	Speed Range	1:200				
	Speed Stability Accuracy	±0.5%, SF	VC			
	Overload Capacity	G Type 60s for 150%; 3s for 180% of rated curre P Type 60s for 120%; 3s for 150% of rated curre				
	Torque Boost	Auto-boost; Manuals adjust range 0.1%~30.0%				
	V/F Curve	Linear/ Multi-Point and N-th Power V/F Curve				
	V/F Separation	Full Separation and Half Separation				
	Ramp Mode	Straight-Line Ramp; S-Curve Ramp 4 Groups of Acce-tion/Dece-tion time	0.0-6500.0s			
	DC Braking	DC Braking Frequency Braking Time Braking Action Current Value	0.0Hz to Max. frequency 0.0s~36.0s 0.0%~100.0%			
on	JOG control	JOG Frequency Range JOG Acceleration/Deceleration Time	0.00 Hz-50.00 Hz 0-6500.0s			
Basic Function	Simple PLC, Multiple Preset Speed	It Implements up to 16 Speeds via the Simple PLC Function or Combination of Terminal States				
sic	Onboard PID	It Realizes Process Controlled Closed Loop Control System Easily				
Ba	Auto voltage regulation (AVR)	It Can Keep Constant Output Voltage A when the Mains Voltage Changes	utomatically			
	Overvoltage/ Overcurrent Stall Control	The current and voltage are limited aut process so as to avoide Frequent Tripping It Helps to Avoid Frequent Over Curren	Due to Overvoltage/Over Current.			
	Rapid Current Limit					
	Torque Limit and Control	It can Limit the Torque Automatically a Over Current Tripping During the Runi	ng Process.			
	Multi-Pumps control	Can realize 1 contrl 2-3, add expasion max.4 pumps	water supply card, can realize			
	Running Command Channel	Given by the Panel, Control Terminals, S Port, can be Switched by Many Ways.				
	Frequency Source	10 Frequency Sources. Digital, Analog Volt. Port. You can Perform Switchover Betwee				
	Auxiliary Frequency Source	10 Multiple Auxiliary frequency source. Fle frequency fine-tuning and frequency synt				
	Timing set/ Communication	0.0-6500.0 min.,	′ RS485			
put	Input Terminal	6 Digital Input terminal 2 Analog Input Terminals, 1 of Which Only Other Supports 0-10V or 4-20mA				
Input & Output	Output Terminal	Digital Output Terminal Relay Output Terminal Analog Output Terminal, That Supports Current Output or 0-10V Voltage Output				
	Protection Function	Output phase loss, overcurrent, overvoltage, overload protections, etc.	ge, undervoltage, overheat			



APV

Integrated Pumps Drives -Wall-Mounted Type 220 / 380VAC; 1HP - 3HP

- Compact, Directly Mounted on Motors
- Robust Enclosure, High Protection Class
- Easy to Use, installation
- Advanced Pumps Control Function
- V/F Control; Max. output frequency 999.9 Hz

APV - Integrated Pumps Control

APV is a new generation of high-end intelligent integrated ultrahigh protection water supply special products independently researched and developed by $\,NIETZ$

The Variable Speed Drives is dustproof and waterproof, and can be installed on various brands of pump motor terminal boxes, and can be accessed in various types of sensor signal. Can be use in dirty and damp environments, even with low pressure jets; saving panel space and cost.

- Compact & Robust
- Easy to use, directly mounted on motor pumps.
- Protection class IP65, can be use at outdoor, dusty, moist

 In order to mechanically install the drive controller on the motor, the adapter is used in place of the terminal box. any motor can be adapted.



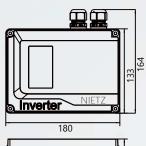
0.75 0.75 16 12 7.2 4.5 220V ±15% 25 1 Phase Input, 1.5 1.5 18 10 7 3 Phase output 2.2 2.5 32 25 16 10 380V ±15% 0.75 0.75 6 9 2.5 3 Phase Input, 1.5 0.75 10 9 5 3.7 3 Phase output 2.2 0.75 10 9 5.8 5

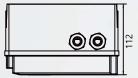


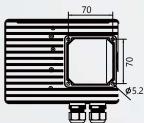
Compact & robust Aluminum heat sink Simple mounting on motor



Dimenstion, mm









CV20

Solution for Industrial Crane and Hoist

- Sensorless Vector Control, Closed-Loop Vector Control
- Professional brake timing control; start and stop smoothly without slipping the hook to prevent the cargo from sliding down
- Intelligent anti-sway, Load holding function
- Built-in Brake Unit, Heave Duty





Professional brake timing control

According to the frequency, output current and torque of the inverter, the brake release command will be output. When starting and stopping, keep the necessary torque to stabilize the cargo, and open the holding brake, and start / stop smoothly without slipping



Brake failure detection

When the stop brake is valid, the encoder is used to detect whether the brake is invalid. If it fails, the inverter is automatically started to maintain torque to prevent accidents (Valid Closed Loop).

Light load speed increase adaptive

Through the light load speed-increasing function, the best running speed matching the load can be achieved. When the load is light, it allows automatic speed increase and improves efficiency, no auxiliary ho ok design is required, which can shorten the operating period of the crane witha long head.





With built-in anti-sway function, so can suppress the shaking of the goods during translation. Since the load does not sway, it can be laid down faster, which is beneficial to shorten the operating cycle. CV20 drives with integrated sensorless control functionality enhance productivity and safety by avoiding sway in cranes.

Stroke Limit Control

By the limit sensor input can prevent the hook from overtraveling and excessive hoisting.



Open and Closed Loop Control

CV20 drives help to ensure excellent open-loop crane performance without encoders. Travel and hoist commissioning is simple. Droop control equalizes torque between the two motors operating in parallel. Closed loop control offers even better crane dynamics. We offer flexible encoder interfaces for broad component choice.

Crane Types Served

- Bridge crane, Overhead crane, Process crane
- Rail-mounted gantry crane, Goliath crane
- Rubber tired gantry crane, RTG crane, Grab crane
- Marine crane, Mobile crane, Mobile harbor cane
- Ship to shore crane (STS crane), container crane
- Tower crane, Construction hoist, Port Crane



 $\mbox{CV20}$ AC drives with built-in crane control software, brake unit and range of safety functions help various types of cranes move efficiently. Our CV20 drives are an excellent choice for standalone cranes

CV20 series inverter special for hoisting is tailor-made for various severe application conditions in the hoisting industry, and it can easily solve technical and performance problems.

CV20 adopts vector frequency conversion control technology, while maintaining excellent performance and function, from the perspective of lifting application, it is superior in terms of ease of use, maintainability, environmental protection, installation space and design standards to similar products. With high-performance current vector technology, it can easily drive asynchronous induction motors to meet the working requirements in various environments

► Features

Rope Length Detection

The height information of the hook can be seen in the cab just by the inverter. When the wire rope reaches the set length, the collision with the lifting drum can be avoided by reducing the ascent and descent speed.

Rapid Deceleration

By inputting a quick stop command through the terminal, it can perform rapid deceleration near the target position.

Load Holding Function

When stopped, the load can be kept at the current position through zero-speed control. Close the brake when it is stable.

Overload Detection

The torque rise value is detected when the cargo accidentally contacts other objects. At this time, the motor can be automatically stopped to prevent accidents and improve safety.

Self-Tuning Motor Parameter

It can accurately identify asynchronous induction motors and achieve high-performance vector control; It can achieve accurate setting of motor parameters of long-distance ower cables under load, and can automatically discriminate encoder signal directions under encoder conditions, simplifying the debugging process.

Parameter macro

The function to select the purpose according to the crane action. Just select hoist, long travel, trolley and other uses, you can automatically set the necessary and unnecessary functions to be valid or invalid. The best parameters can be set simply for different purposes.





ESD / ESD2

For Small Power AC Motors

- Mini Dimension, Low Cost
- Potentionmeter Knob to Covenient Adjust to Speed Regulation, Optimized Structure
- ESD2 series Support MODBUS via RS485
- V/F Control; 220V, Easy to use
- Frequency Range 1.0...99.0Hz/ 0.0...300.0Hz

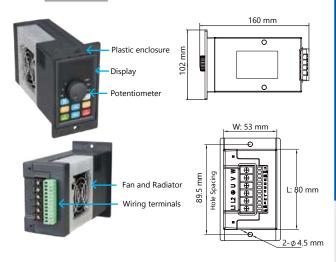
ESD2 Variable Speed Drives

ESD2 series frequency inverter is a new generation micro power variable speed drive, specially designed for small power motor. Micro dimension, save installation space, instrument embedded structure, installation is simple and compact.

Advantage and Features

- Power range: 0.2~1.1 kW / 220V; V / F type control
- Input / output: single / three phase
- Output frequency range 0-300 Hz, analog input 0-5 V
- Carrier frequency up to 38.4 kHz
- Built-in MODBUS RS485, baud rate up to 9600 bps
- Forced air cooling
- Potentiometer knob to convenient adjust to speed regulation, optimized structure, forced air cooling
- Adopt a new generation I P M module with complete protection functions

DIMENSION

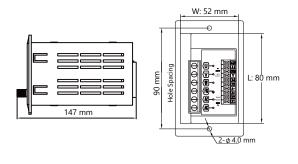


ESD Variable Speed Drives

ESD frequency inverter is embedded small power inverter, specially designed for small power motor. Small dimension, save installation space, instrument embedded structure, installation is simple and easy to use.

Advantage and Features

- Power range: 0.4~0.75 kW / 220V; V / F type control
- Input / output: single / three phase
- Output frequency range 1-99 Hz
- With speed adjust potential device, also can outer connect speed adjust potential device;
- Built-in MODBUS RS485, baud rate up to 9600 bps
- Interior configured intelligent logic controller can realize the simple, easy logic control function.
- With electric thermal electric relay function and other traditional motor protection device;
- Can outer connect LED for indicate, convenient for field use requirements;
- Humanization operating interface, simple and clear the parameters setting, convenient for operating;



Typical Applications

Suitable for electronic equipment, package equipments, wood cutting machine, transportation belt, wire drawing machine, etc.



AMD

AC Spindle Servo Drives / 380V, 0.4-160 kW

- V/F Control, SFVC, FVC Control Mode
- Controls AC Induction, Spindle Asynchronous Motor
- Support Various Optional Encoder
- Easy and flexible control; MODBUS RS485
- Increadible Performance of Speed, torque and position control; All protection





AMD series spindle servo drives is designed for numerical control machine of new type and high precision and it has new functions like positioning control, pulse synchronous control and so on. It supports FEEDBACK vector control towards the spindle motor with encoder. This drive has high responding ability towards speed as well as smooth speed. It can achieve various functions like warrant stop of spindle; Rigid tapping; indexing positioning and so on by cooperating with different numerical control system.

▶ Features

- Multi encoder support; it can support differential encoder; ABZ encoder and so on.
- Power dip ride-through, load feedback energy compensates for any voltage reduction, allowing the drive to continue to operate for a short time during power dips.
- Overvoltage and overcurrent stall control; the system limits the output current and voltage automatically during operation to prevent frequent or excessive trips.
- Torque limit and control: the system limits the torque automatically to prevent frequent overcurrent tripping during operation. Torque control is applied in vector control.
- Onboard multiple preset position: the system implements up to 16 position by using simple PLC function or by using digital input signals.

TYPICAL APPLICATION

- CNC lathe, turn-milling machine tool, vertical lathe, Heavy duty horizontal lathe
- Drilling and tapping center, engraving and milling machine, gear hobbing machine, gear shaping machine, gear milling machine











AT10 series

Electrohydraulic Servo Drive



- Support single, double and multiple electro hydraulic pump system
- Variety of signal reference modes, more saving energy
- Buit-in Brake unit. Heavy Duty, 150% in 60s; 180% in 5s.
- Voltage Supply 220 ~ 380 VAC; Powerfull 7.5 ~ 450 kW
- Various protection functions such as phase loss, short circuit, overheating detection and etc.
- High-performance servo control: Vector control + field weakening control + PID control
- Support 0-10V DC / 4-20mA direct analog signal input
- Fast and safe isolated terminal wiring
- Performance Start torque: 0Hz 180%; Steady speed accuracy: ± 0.02%; Torque control accuracy: ± 5%
- Air cooling, liquid cooling way, Flexibility to use

Electro-Hydraulic ServoSystem combined both electrical and hydraulic characteristics can accurately follow the command changes to adjust the output. With high precision, fast response, big output power, flexible signal processing, easy to control, etc., it is widely used in various industries such as in Injection molding machines, hydraulic presses, stamping and bending machines, etc.

► ADVANTAGE

✓ Save Energy Consumption

Optimized pressure and flow control algorithm saving energy max. 80%

✓ High Precision, Intelligence

Multiple Control modes of speed loop, current loop and pressure loop to ensure high precision repeatability.

✓ Noise Reduction

Efficient reduction of Noise, less than 65dB improve equipments usage environment

✓ Save Volume and Place

Suitable PM Synchronous Motor, Compact size Compared with the open hydraulic circuit, save 75% tank volume

	Item	Specifications				
С	ontrol Mode	V/F Control / Closed Loop Ve	ctor Control			
Carrier frequency setting		1-12.0 kHz Automatically adjust the carrier frequency according to the load characteristics.				
	Output Frequency Range		0.0-599.00 Hz			
	Frequency Setting Resolution	Digital Input Analog Input	0.1 Hz 0.025% of Max. Output Frequency			
	Startup Torque	0.0 Hz /180%				
	Speed Range	1:1000 (FVC Mode Control)				
	Overload Capacity	150% of rated current, 60s; 18	30% of rated current, 5s			
	Torque Control Accuracy	± 5% (FVC Mode Control)				
ے	Steady Speed Accuracy	± 0.02% (FVC Mode Control)				
icatio	Acceleration and deceleration curves		eleration. 4 kinds of ace-tion minus time range 0.0 ~ 6500.0s.			
Basic Specification	Fast Current Limiting Function	Min. Overcurrent faults,Protecto normal operation	ct the ServoDrive			
asic	Encoder Support	Resolver Encoder				
В	Overvoltage/ Overcurrent Stall Control	Automatically limits the current and voltage during running to avoid frequent tripping caused by overvoltage / overcur				
	Communication	RS-485 and CANbus				
	Protection Functions	I/O phase loss protection, over current protection, over vo protection, under voltage protection, overheat protection overload protection				

Typical Applications

- Air compressor, Pumping unit in oil field, etc.
- Injection molding machines, hydraulic presses, stamping and bending machines, etc.





► Flow-Converging and Dividing System Multi-Pump Flow-Converging System CAN bus Pressure Pressure Command Drive Feedback Oil Inlet Port Pump B Pump C Pump A Pressure Sensor Oil Outlet Port Multi-Pump Distributed Flow System CAN bus Pressure Pressure Pressure Command. Slave Pressure Command. Pressure Command. Slave Pressure Command. 3 Pressure Feedback.1 Pressure Pressure eedback.3 Oil Inlet Port

Set the same speed for motors through communication

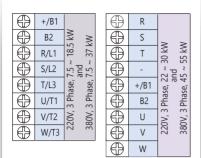
Oil Outlet Port 1

 Control the convergent/distributed flow of pumps 2 and 3 by powering on and off solenoid valves ①,②, ③, and ④

Oil Outlet Port 2

- When the convergent flow control is enabled, the pressure and flow references and pressure feedback signals received by slave drives are invalid.
- When the distributed flow control is enabled, the CAN communication references received by slave drives are invalid.

Oil Outlet Port 3

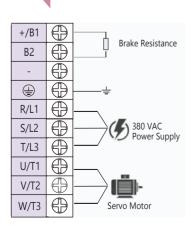


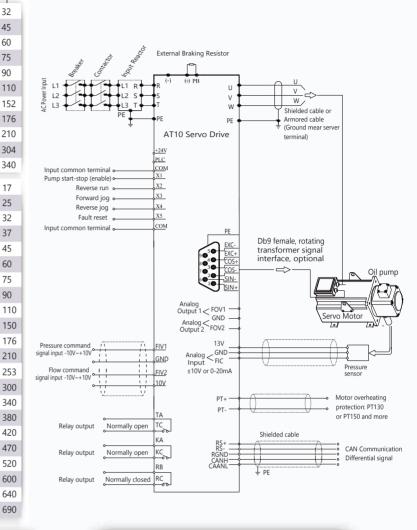
	R		1	R	
\oplus	S	≥		S	Š
(Т	N 110	0	Т	160
(+/B1	55 kV and 75 ~		B2	75 kW and 132 ~ 160 kW
\oplus	B2	220V, 3 Phase, 55 kW and 380V, 3 Phase, 75 ~ 110 kW		-	1 - 10 1
	-	, 3 P	0	+/B1	220V, 3 Phase, 380V, 3 Phase,
(i)	U	220V 380V	0	U	20V, 80V,
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	W		(A)	W	

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		F)		2011 2 81	00.114

220V, 3 Phase, 90 kW and 380V, 3 Phase, 132~160 kW

Terminal Code	Function
R/L1, S/L2, T/L3	Voltage Input
U/TI, V/T2, W/T3	Output Terminal of Drive Connect to AC Motor 3 ph.
+/B1, -	DC Power + / -; Can be connect to Brake Unit
+/B1, B2	Connect to Brake Resitance
=	Ground Terminal
(+)/(-)	Brake Unit Terminal



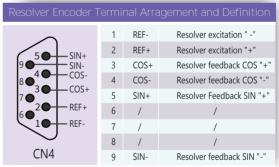


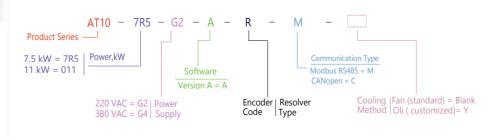


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18.5

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Micro AC Drive

High Performace General Purpose

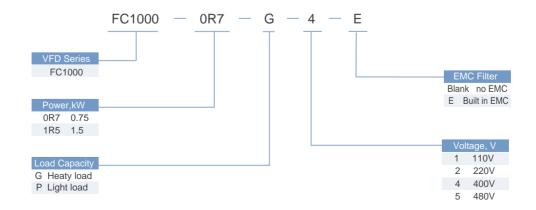




The FC1000 family offers a compact AC drive that combines easy operation with high-efficiency control for AC induction, PMS motor. The robust compact designed, various controls mode, support EtherCAT, Modbus, Profibus-DP communication, built-in EMC filter, 24DC, STO function, Extersion PG Cards.....

- · Cost Effective; Micro Compact Design
- Easy to use and install; DIN rail mount, RJ45 interface keypad cable
- · Integrated safety Safe Torque Off feature
- · Built-in EMC Filter, 24VDC power resurce, PID
- V/F, Sensorless Vector, Closed-Loop Vector Controls mode
- · Frequency range 0~599Hz; Power Range 0.4~450 kW
- Automatic Voltage Regulation; Performance Load features
- Support Various Extersion Cards; EtherCAT, Profibus-DP, Modbus TCP, Digital I/O
- External Keypad copy function and automatic parameter back-up

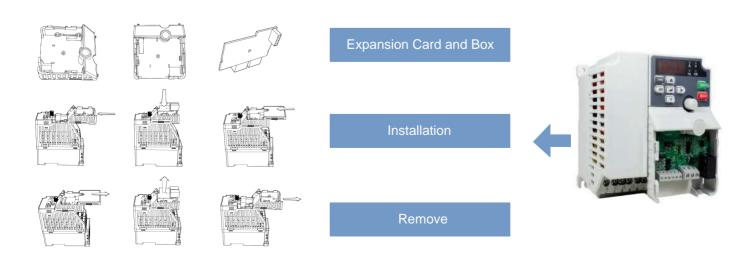
Ordering Guide



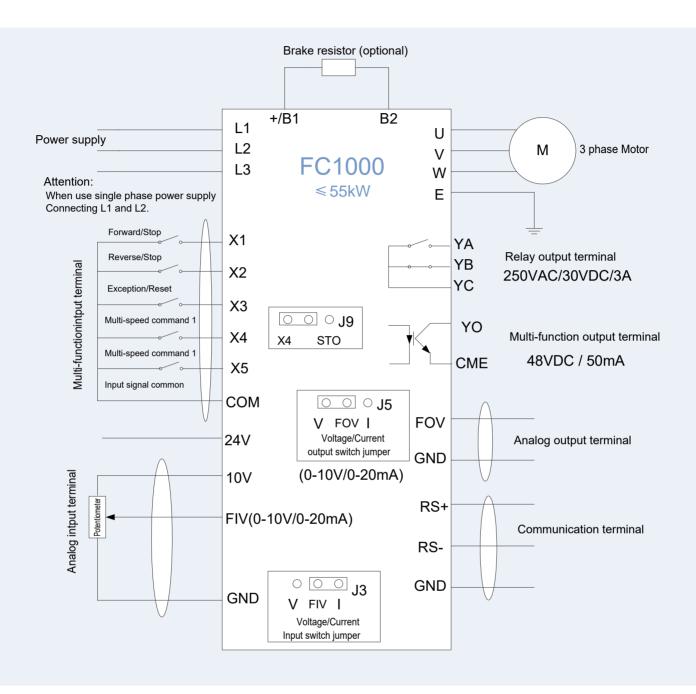
Specification of FC1000



Installation and removal of expansion cards (≤ 55kW)



General Connection Diagram





PC Software tools

If you are looking to keep a backup copy of parameter set or need to customize the drive's functionality to match your application, the FC1000 has the PC software tools to help.

Specification of FC1000

Control Mode Sersoless Flav Netror Control, PVC Max, Frequency Vector Control Vector Control Vector Control O0-5990 Hz V/F Control O0-1200 Hz D01 Hz Analog Setting Max, Frequency x 0.025% Save C G Type O5 Hz / 100% Speed Range Speed Sability Accuracy Speed Range Speed Sability Accuracy Speed Range Speed Sability Accuracy Overload Capacity P Type GS for 120% of the Rated Current, 3s for 180% of the Rated Current, Sfor 120% of the Rated Current, 3s for 150% of the Rated Current, Sfor 120% of the Rate	Item		Specifications				
Max. Frequency		Control Mode	V/F Control				
Carrier Frequency The Carrier Frequency is Automatically Adjusted Based on the Load Features.		Max. Frequency					
Start Torque Start Torque Start Torque P Type 0.5 Hz / 150%, SPVC		Carrier Frequency					
Speed Range Speed Stability Accuracy Speed Stability Accuracy Overload Capacity OPTOP Overload Capacit		Input Frequency Resolution					
Speed Stability Accuracy \$10.5%, SFVC Type 60s for 150% of the Rated Current, 3s for 180% of the Rated Current. P Type 60s for 120% of the Rated Current, 3s for 150% of the Rated Current. P Type 60s for 120% of the Rated Current, 3s for 150% of the Rated Current. P Type 60s for 120% of the Rated Current, 3s for 150% of the Rated Current. P Type 60s for 120% of the Rated Current, 3s for 150% of the Rated Current. P Type 60s for 120% of the Rated Current, 3s for 150% of the Rated Current. P Type 60s for 120% of the Rated Current, 3s for 150% of the Rated Current. P Type 60s for 120% of the Rated Current, 3s for 150% of the Rated Current. P Type 60s for 120% of the Rated Current, 2s for 150% of the Rated Current. P Type 60s for 120% of the Rated Current, 2s for 150% of the Rated Current. P Type 60s for 120% of the Rated Current, 2s for 150% of the Rated Current. P Type 60s for 120% of the Rated Current P Type 60s for 120% of the		Start Torque	, , , , , , , , , , , , , , , , , , ,				
Overload Capacity Torque Boost Ramp Mode DC Braking DC Braking JOG control JOG control Auti voltage regulation (AVR) Overvoltage / Overcurrent Stall Control Rapid Current Limit Torque Limit and Control Rapid Current Limit Torque Limit and Control Running Command Channel Fixed Boost: Customized Boost: Control of Asynchronous Motor are Implemented Through the High-Performance Current Vector Control Terminal Frequency Source Auxiliary Frequency Source Timing Command Channel Given by the Poale, Control Setting, You can Perform Switchover Between these Sources in Vanious Ways. Torque Limit and Control Residency Source Auxiliary Frequency Source Timing Control Output Terminal Li Edia Coupt Terminal Li Edia Output Terminal Li Digital Output Terminal Li Lock line Keys So as to Prevent Mis-Function. Reys so as to Prevent Mis-Function. Reys so as to Prevent Mis-Function. Reys so as to Prevent Mis-Function.		1 9	·				
Overload Capacity P Type 60s for 120% of the Rated Current, 3s for 150% of the Rated Current. Torque Boost Fixed Boost; Customized Boost 0.15%-30.0% Straight-Line Ramp; S-Curve Ramp Four Groups of Acceleration/Deceleration Time with the Range of 0.00-6500.0s DC Braking Frequency 0.00HzMaximum frequency Braking Time 0.05-100.0% Braking Time 0.05-100.0% JOG Frequency Range 0.00 Hz-50.00 Hz JOG Acceleration/Deceleration Time: 0.05-6500.0s It Implements up to 16 Speeds via the Simple PLC Function or Combination of Terminal States It Realizes Process Controlled Closed Loop Control System Easily Auto voltage regulation (AVR) Overvoltage / Overcurrent Stall Control Rapid Current Limit Torque Limit and Control Rapid Current Limit It helps to Avoid Frequent Over Current Faults of the AC Drive. High Performance Running Command Channel Frequency Source Auxiliary Frequency Source Timing Command Channel Frequency Source There are Ten Frequency Sources. Digital Setting, Analog Voltage Setting, Analog Current Setting, Pulse Setting, Profibus-DP, CAN is optional Input Terminal Output Terminal Protection Function Notor Shourt-Circuit Detection at Power-Ch, Output Phase Loss Protection, Over-Current Protection Overheat Protection and Overload It can Lock the Keys oa so to Prevent Ms. Function and Deventad It can Lock the Keys oa so to Prevent Ms. Function, Over-Current Protection Some Keys oa so to Prevent Ms. Function.		Speed Stability Accuracy					
Straight-Line Ramp: S-Curve Ramp Four Groups of Acceleration/Deceleration Time with the Range of 0.00-6500.0s		Overload Capacity	71				
DC Braking DC Braking Frequency DC Braking Action Current Value DC Braking Frequency Braking Action Loop- DC Braking Frequency Braking Time DC Braking Action Current Value DC Braking Frequency DC Braking Frequenc		Torque Boost	Fixed Boost; Customized Boost 0.1%~30.0%				
Braking Time 0.0s~100.0s Braking Action Current Value 0.0%~100.0% JOG control JOG Acceleration/Deceleration Time: 0.0s~6500.0s Simple PLC, Multiple Preset Speeds It Implements up to 16 Speeds via the Simple PLC Function or Combination of Terminal States Onboard PID It Realizes Process Controlled Closed Loop Control System Easily Auto voltage regulation (AVR) It Can Keep Constant Output Voltage Automatically when the Mains Voltage Changes The current and voltage are limited automatically during the running process so as to avoid Frequent Limit Torque Limit and Control It can Limit the Torque Automatically and Prevent Frequent Over Current Tripping During the Runing Process. High Performance Control of Asynchronous Motor are Implemented Through the High-Performance Current Vector Control Technology. Running Command Channel Given by the Panel, Control Terminals, Serial Communication Port, can be Switched by Many Ways. There are Ten Frequency Sources. Digital Setting, Analog Voltage Setting, Analog Current Setting, Pulse Setting, Serial Port Setting, Vou can Perform Switchover Between these Sources in Various Ways. Input Terminal Joking Input Terminal, One of Which Supports up to 100 kHz High-Speed Pulse Input 1 Analog Output Terminal 1 Relay Output Terminal 1		Ramp Mode	3				
Auto voltage regulation (AVR) It Can Keep Constant Output Voltage Automatically when the Mains Voltage Changes The current and voltage are limited automatically during the running process so as to avoid Frequent Tripping Due to Overvoltage/Over Current. Rapid Current Limit Torque Limit and Control It can Limit the Torque Automatically and Prevent Frequent Over Current Tripping During the Runing Process. High Performance Control of Asynchronous Motor are Implemented Through the High-Performance Current Vector Control Technology. Running Command Channel Given by the Panel, Control Terminals, Serial Communication Port, can be Switched by Many Ways. There are Ten Frequency Sources. Digital Setting, Analog Voltage Setting, Analog Current Setting, Pulse Setting, Serial Port Setting. You can Perform Switchover Between these Sources in Various Ways. Auxiliary Frequency Source 10 kinds of Frequency Sorce, can be easily realize Micro Adjust, Frequency Synthesizer Timing Control Communication Methods RS 485, EtherCAT, Profibus-DP, CAN is optional 5 Digital Input Terminals, One of Which Supports up to 100 kHz High-Speed Pulse Input 1 Analog Input Terminal, One of Which Only Supports 0-10V Voltage Input or 4-20mA current input. 1 Digital Output Terminal 1 Relay Output Terminal 1 Relay Output Terminal 1 Analog Output Terminal, That Supports 0-20mA Current Output or 0-10V Voltage Output Motor Shourt-Circuit Detection at Power-On, Output Phase Loss Protection, Over-Current Protection Come Keys so as to Prevent Mis-Function.	uc	DC Braking	Braking Time 0.0s~100.0s				
Auto voltage regulation (AVR) It Can Keep Constant Output Voltage Automatically when the Mains Voltage Changes The current and voltage are limited automatically during the running process so as to avoid Frequent Tripping Due to Overvoltage/Over Current. Rapid Current Limit Torque Limit and Control It can Limit the Torque Automatically and Prevent Frequent Over Current Tripping During the Runing Process. High Performance Control of Asynchronous Motor are Implemented Through the High-Performance Current Vector Control Technology. Running Command Channel Given by the Panel, Control Terminals, Serial Communication Port, can be Switched by Many Ways. There are Ten Frequency Sources. Digital Setting, Analog Voltage Setting, Analog Current Setting, Pulse Setting, Serial Port Setting. You can Perform Switchover Between these Sources in Various Ways. Auxiliary Frequency Source 10 kinds of Frequency Sorce, can be easily realize Micro Adjust, Frequency Synthesizer Timing Control Communication Methods RS 485, EtherCAT, Profibus-DP, CAN is optional 5 Digital Input Terminals, One of Which Supports up to 100 kHz High-Speed Pulse Input 1 Analog Input Terminal, One of Which Only Supports 0-10V Voltage Input or 4-20mA current input. 1 Digital Output Terminal 1 Relay Output Terminal 1 Relay Output Terminal 1 Analog Output Terminal, That Supports 0-20mA Current Output or 0-10V Voltage Output Motor Shourt-Circuit Detection at Power-On, Output Phase Loss Protection, Over-Current Protection Come Keys so as to Prevent Mis-Function.	Functio	JOG control					
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Overvoltage / Overcurrent Stall Control Rapid Current Limit Torque Limit and Control High Performance Control of Asynchronous Motor are Implemented Through the High-Performance Current Vector Control Technology. Running Command Channel Given by the Panel, Control Terminals, Serial Communication Port, can be Switched by Many Ways. There are Ten Frequency Source. Auxiliary Frequency Source Timing Control Communication Methods RS 485, EtherCAT, Profibus-DP, CAN is optional Input Terminal Output Terminal Protection Function Key Locking and Function Selection Key Locking and Function Selection Tick Avoid Frequent Voltage are limited automatically and perior frequent. There are Ten Limit do Averond Terminals, and Prevent Frequent Over Current Tripping During the Runing Process. Control of Asynchronous Motor are Implemented Through the High-Performance Current Vector Control Terminals, Serial Communication Port, can be Switched by Many Ways. There are Ten Frequency Sources. Digital Setting, Analog Voltage Setting, Analog Current Setting, Pulse Setting, Serial Port Setting, You can Perform Switchover Between these Sources in Various Ways. Auxiliary Frequency Source 10 kinds of Frequency Sorce, can be easily realize Micro Adjust, Frequency Synthesizer Timing Control 0.0-6500.0 min. Communication Methods RS 485, EtherCAT, Profibus-DP, CAN is optional 1 Input Terminal 1 Relay Output Terminal, One of Which Supports up to 100 kHz High-Speed Pulse Input 1 Analog Input Terminal 1 Relay Output Terminal 1 Relay Output Terminal 1 Relay Output Terminal 1 Analog Output Terminal 1 Control Con	B	Onboard PID	It Realizes Process Controlled Closed Loop Control System Easily				
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Current Output or 0-10V Voltage Output Motor Shourt-Circuit Detection at Power-On, Output Phase Loss Protection, Over-Current Protection , Overheat Protection and Overload It can Lock the Keys Parlially or Completelly and Define the Function Range of Some Keys so as to Prevent Mis-Function.	utput		5 Digital Input Terminals, One of Which Supports up to 100 kHz High-Speed Pulse Input				
Frotection Function , Overheat Protection and Overload It can Lock the Keys Parlially or Completelly and Define the Function Range of Some Keys so as to Prevent Mis-Function.	Input & O	Output Terminal	1 Relay Output Terminal 1 Analog Output Terminal, That Supports 0-20mA				
	Ń	Protection Function					
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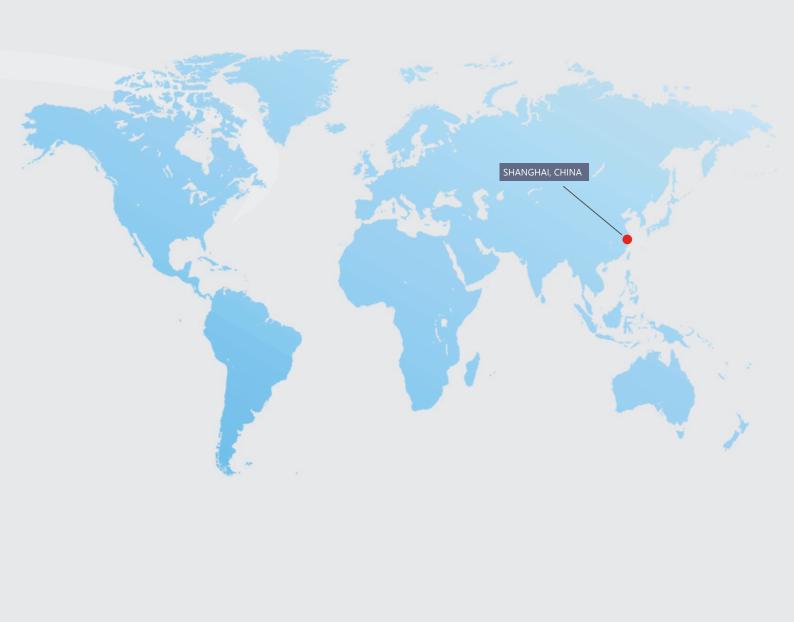


- Fan, Pumps, Converyors, Food processing machinery
- · Packaging machinery, Textiles, Mixers, Air conditioner
- · Water supply System, centrifugal, etc.





OPTIMIZE MOTOR CONTROL



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